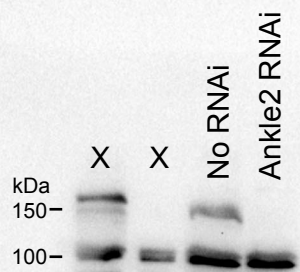


Mat $\alpha$ 4>



$\alpha$ -Ankle2